

Routing Protocol Simulation In A Big Data Environment

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Abstract: *In this study, the proposed routing protocol can be improved further by formulating a mechanism to help nodes gain further knowledge of others inside the network. Without exchanging further message and extra processing burden on nodes, the primary challenge was to enhance the routing protocol, but always kept an eye on avoiding any alteration to the well-designed routing protocol and trying the best not to cause extra overhead that prevents the enhancement from achieving its goal. Overall, we can conclude that simulation for MD-AODV shows the correct implementation of the algorithm and the performance metric results proves the success of the implementation. The simulation result also shows previous two that MD-AODV will cause a slight increase in route discovery. However, it leads to a better End-to-End delay during data transmission.*

1. INTRODUCTION

People want to join and leave networks as they want and do not require sophisticated processes applied by service providers and. It can be a good alternative when these providers are down during disasters or war [1]. The advancement in wireless devices and the increase of data exchange speed, real time applications become a central source for communication among people. Data exchange in MANET requires routes that it should be established before transmission and nodes participating information of the network have to cooperate and use some of its uses different type of routing protocols that can be classified in different ways. The main classification relies on the route discovery policy [2, 3]. Proactive or static routing protocols require routes to be established between all nodes during the formation of the network as in (OLSR and DSDV). Routing tables used to store paths to all nodes inside the network and they are updated periodically. These routing protocols have the advantage of route availability when needed and the disadvantage saw in large networks as it causes overhead and consume resources. While reactive or dynamic routing protocols establishes path when any node have data want to send as in (AODV and DSR) [4]. The advantage of this type is the small size of routing table, as nodes do not require storing information about whole network the disadvantage comes from the delay time needed for route discovery and the delay caused by link break and repair process that leads to further packet retransmission. (Abdul Jalil et al., 2021; Mohd Noh et al., 2021; Mustafa et al., 2021; Roszi et al., 2021; Tumisah et al., 2021). If it is managed well, various problems can be avoided (Irma et al., 2021; Suzana et al., 2021; Rohanida et al., 2021; Nazrah et al., 2021; Shahrulliza et al., 2021).

Combinations of both previous types create a hybrid type of protocols to reduce overhead caused by the two different types. This type usually suits large network in which it is divided to smaller groups called (clusters, zones....etc.) inter-group communication conducted in a

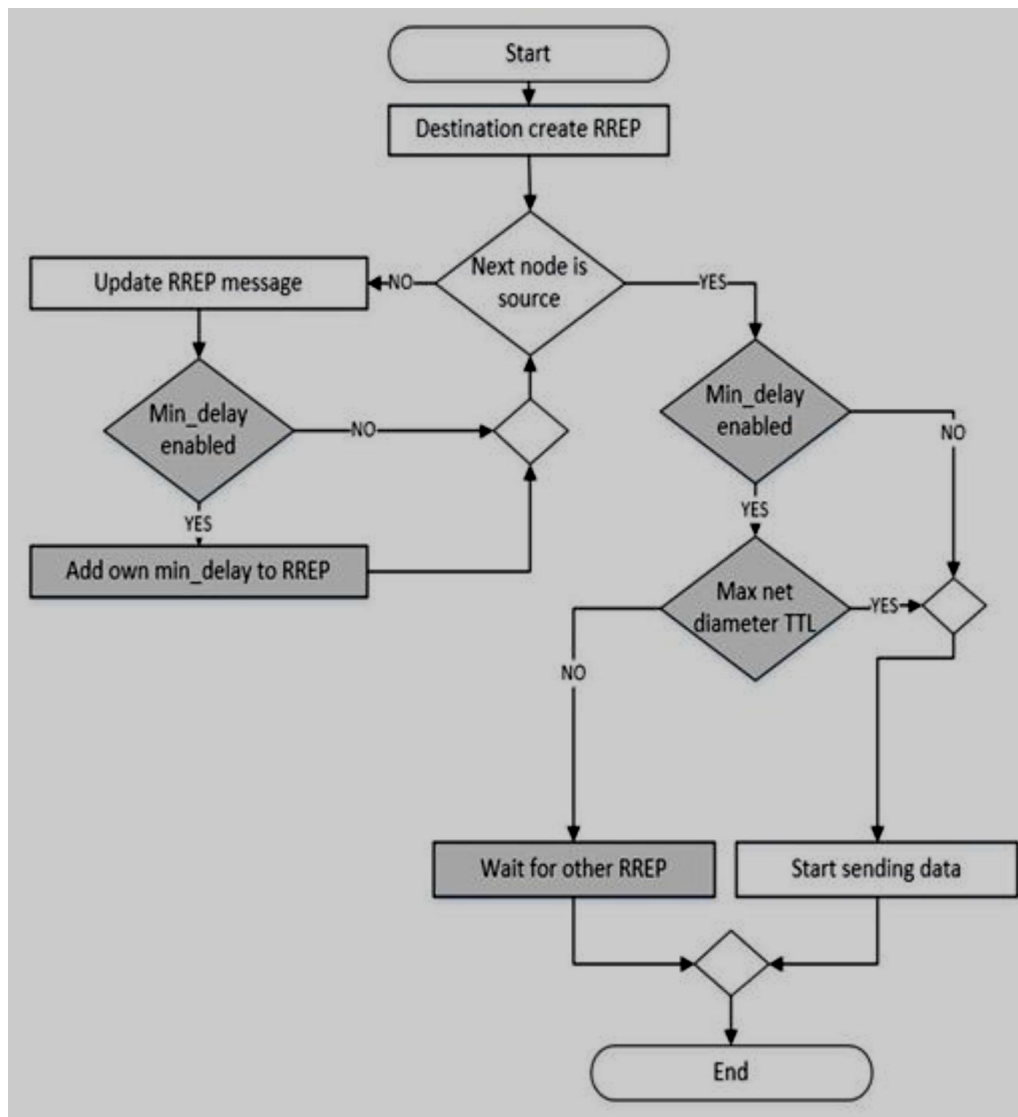
proactive manner while inner-group communication conducted reactively, the disadvantage of these protocols come from the larger memory requirement. All aspects require effective leadership and management (Mohd Arafat et al., 2021; Sumaiyah et al., 2021; Hifzan et al., 2021; Shahrul et al., 2021; Helme et al., 2021).

Generally, nodes in MANET have limited information about others beyond transmission range. On the other hand, QoS provisioning require routes that can guarantee services and for this needs to share nodes capability with others inside the discovered path. Sharing knowledge about other nodes capabilities require the exchange of extra messages that causes overhead and consume resource. Therefore, it is important to use routing protocols that have limited support to QoS. Accordingly, routing protocols messages have to be enhanced to carry extra information about QoS parameters and shared it among nodes residing inside the path [5]. The proposed enhancement modifies the routing protocol and the shortest path concept that relies on number of hops and adds the processing delay of the nodes. The success of something depends on good and efficient management (Mohd Ali et al., 2021; Parimala et al., 2021; Siti Jamilah et al., 2021; Nor Fauziyana et al., 2021; Noel et al., 2021).

2. METHODOLOGY

The proposed modification to AODV routing protocol consists of modification of the RREP process and source node, route selection. Therefore, the RREQ process was executed in the same manner as in normal AODV. While the RREP process, contains the following change:

- 1- A 32 bit field added to the RREP message to store the accumulative value of the Minimum processing delay.
- 2- Starting with the destination every node processes the RREP message insert its own processing delay and forward back the RREP message.
- 3- When the source receives the RREP message it delays the data transmission to allow other RREP messages to arrive until maximum net diameter time expires.
- 4- Then the source compares the minimum delay of each path and the no of hops to select the path. In which is used for data transmission.
- 5- A reference for other paths stored to be used in case of congestion or link breakage.



3. RESULTS AND DISCUSSION

During transmission routing error occurs as a result of link break or congestion, in which route repair starts leading to packet drop and requires retransmission. Simulation results show that both protocols gradually have an increase in the packet retransmission, which is due to increase in the data rate as previously explained. However, we notice that MD-AODV have an average of 50 packets for deferent data rates while the normal AODV have 55. The best way is to do efficient management (Ahmad Shafarin et al., 2021; Junaidah et al., 2021; Farah Adibah et al., 2021; Ahmad Shakani et al., 2021; Muhamad Amin et al., 2021). This demonstrates that the importance of something being managed well (Santibuana et al., 2021; Nor Diana et al., 2021; Zarina et al., 2021; Khairul et al., 2021; Rohani et al., 2021; Badaruddin et al., 2021, Abdul Rasid et al., 2021).

This is another indication that a path with less delay causes fewer packets to get dropped and retransmitted again. The PDR for both protocols shows an increase of 0.1msec on average in favor of MD-AODV, because of the enhancement avoids paths that contain nodes with high processing delay, which in return leads more packet drop that in result leads to less PDR.

We notice from the simulation result that the RDT pattern is similar to previous scenario. The average RDT for AODV is 1.5msec while for MD-AODV is 2.5msec on average. This time the differences between the two protocols are increased to 1 msec or 0.9msec more for MD-AODV. This is due to the mobility of the nodes which forces the source to take longer time to select a path and start transmitting the data.

The simulation result shows a similar impact for nodes mobility on the End-to-End delay for both AODV versions with an increase of approximate 0.5 msec on average. Furthermore, and for the same reason we notice that the delay increases for MD-AODV this time increase with data rate. Unlike the previous scenario, the PR results of this simulation show that the packet retransmission pattern varies for different data rates, this is due to the movement of the nodes. However, we see similarity in the advantage of MD-AODV of 7.28 packets on average. Furthermore, different results changed when the simulation was repeated several times but the pattern and advantage of MD-AODV stayed the same on average. Simulation result shows a reduction in PDR which is due to packets drops occurs due to nodes movement, but MD-AODV still have the advantage of 0.912 to 0.855 for AODV because of node processing delay. Indeed, MANET routing protocol improvement motivated researchers to explore different ways to enhance its support to QoS. In this section, we explore some of these efforts and analyze the results. A Research study evaluated different reactive routing protocol support to QoS, and for this purpose AODV, DSR and TORA protocols considered. The review studies many different parameters such as (route discovery, packet delivery and delay). The result show different performance for each protocol, but overall AODV outperforms the other protocols. Load-Balancing DSR Based QoS Routing Protocol in MANETs (RTL-B-DSR) is another enhanced routing protocol that adds some QoS parameters to DSR protocol to achieve adaptability and strengthen the protocol [2]. Various policies applied to obtain flexibility for load balancing. The promising results obtained from different scenarios prove that adding some of QoS metrics to routing protocols will improve the performance and a similar approach was adopted in our work. A different concept in another research tries to reduce the overhead caused by link break of paths due to mobility, which in return requires constant route discovery attempts. The proposed method tries to minimize the broadcast messages.

CNN Keras is an open-source neural network library written in Python. It provides an API version of the neural network model making an easier way to create and train our model. In our case, we used sequential, Conv2D, call-backs API. First of all, to get image shape `get_image_size` function is called, this method reads the image thorough `imread` method and returns the shape of the image in `x` and `y` variables. In it, the Sequential model is used, and then the `conv2D` method is used for recognizing the pattern. And these patterns are stored in the form of filters of shape `5x5`. In the starting layer, we used 32 filters with activation function `relu()`, our model is recognizing the edges and later part, it recognizing the final shape of the object, that together helped to classify the object in the image where we have used 128 filters of shape `5x5`.

To optimize our model accuracy of learning or value of parameters to maximize accuracy, we have used an optimizing algorithm known as stochastic gradient descent; it is a rectified version of gradient descent. It is a faster technique. To prevent our model from overfitting problems, we used a state of art i.e. using dropout API. To decide the epochs value to achieve certain level accuracy in the training part, instead of passing direct values, we have used a method of Keras library called as call-backs / checkpoints through which we can control various parameters like to stop training part after a certain point, to prevent overfitting, etc. automatically. For pre-processing of data, to load images we have used python libraries

called pickle and converted the final training labels of the data set into a categorical format using np_utilspyhton library.

```
Epoch 00001: val_acc improved from -inf to 0.90846, saving model to cnn_model_keras2.h5
Epoch 2/20

100/12999 [.....] - ETA: 56s - loss: 1.4564 - acc: 0.8400
200/12999 [.....] - ETA: 57s - loss: 1.8081 - acc: 0.8300
300/12999 [.....] - ETA: 56s - loss: 1.7551 - acc: 0.8300
400/12999 [.....] - ETA: 57s - loss: 1.7893 - acc: 0.8175
500/12999 [>.....] - ETA: 57s - loss: 1.8356 - acc: 0.8120
600/12999 [>.....] - ETA: 56s - loss: 1.7665 - acc: 0.8183
700/12999 [>.....] - ETA: 55s - loss: 1.8349 - acc: 0.8114
800/12999 [>.....] - ETA: 55s - loss: 1.8150 - acc: 0.8162
900/12999 [=>.....] - ETA: 54s - loss: 1.8390 - acc: 0.8200
1000/12999 [=>.....] - ETA: 54s - loss: 1.7837 - acc: 0.8220
1100/12999 [=>.....] - ETA: 54s - loss: 1.8146 - acc: 0.8218
```

The model that was created by the CNN Keras is loaded. The webcam starts using the VideoCapture class which saves the gesture input by the user. It is converted to the standard in which it can be compared with the gestures stored in the model. The resultant gesture is passed on to the predict() function which predicts the probability of matching the gesture with stored gestures. The stored gesture with the maximum probability is selected and the label/class corresponding to the selected gesture is returned.

The histogram created by the Setting Hand Histogram is loaded. The user is asked to enter the first operand which is read and recorded by VideoCapture class and cropped into smaller pieces i.e. images. These images are then flipped vertically by using the flip() function. For color conversion of the images, we used the function cvtColor(). The back-projection of the resultant images is calculated based on the stored histogram. The kernel used is ellipse which is obtained by getStructuringElement() which is convolved with the back projection histogram by filter2D(). The resultant image is then blurred using Gaussian and Median filter. The thresholding of the image is done to get a proper hand out of frame. Then the threshold output is converted into a greyscale image. Then the image is recognized as described in the previous paragraph. To input the operator, we have assigned the different type of operations to the numerical values, for example, 1 for Addition (+), 2 for Subtraction (-). The second operand is entered in the same way as we entered the first one. Once we are done with entering the second operand, a “confirm” symbol must be given as input to the System so that the System calculates the result based on the input and display it on the screen.

4. CONCLUSION

This research work presented in this paper shows that routing protocol can be improved further by formulating a mechanism to help nodes gain further knowledge of others inside the network. Without exchanging further message and extra processing burden on nodes, the primary challenge was to enhance the routing protocol but I always kept an eye on avoiding any alteration to the well-designed routing protocol and trying the best not to cause extra overhead that prevents the enhancement from achieving its goal. Overall, we can conclude that simulation for MD-AODV shows the correct implementation of the algorithm and the performance metric results proves the success of the implementation. This simulation result

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